

COMMANDIA

ERDF budget: 942.832,31 €

Project funded by the Interreg Sudoe Programme through the European Regional Development Fund (ERDF)

Collaborative robotic mobile manipulation of deformable objects in industrial applications

Consortium

SIGMA Clermont

INESCOP

Universidad de Zaragoza - I3A

Universidad de Alicante

Universidade de Coimbra



Cooperation depends on you

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